

統計数理研 2013-9-26

情報幾何入門

理研 脳科学総合研究所

甘利俊一

Manifold of Probability Distributions

Fisher metric : 1929 H. Hotelling
1945 C.R. Rao

Invariance : 1972 N.N. Chentsov
connections

Curvature : 1978 B. Efron (A.P. Dawid)

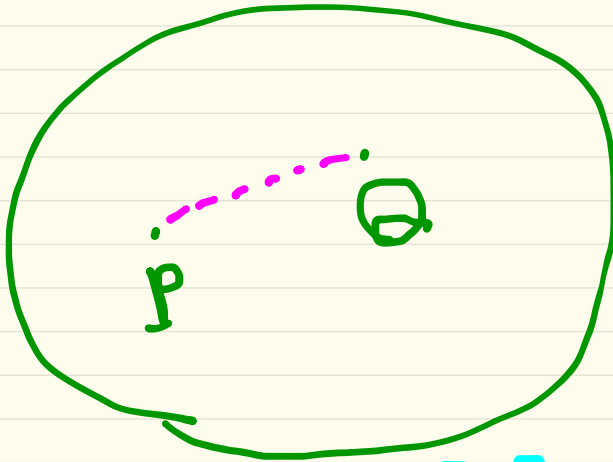
Duality : 1982 S. Amari
H. Nagaoka & S. Amari

... many others G. Pistone J.L. Koszul

applications

Manifold and Divergence

Dually Flat Structure

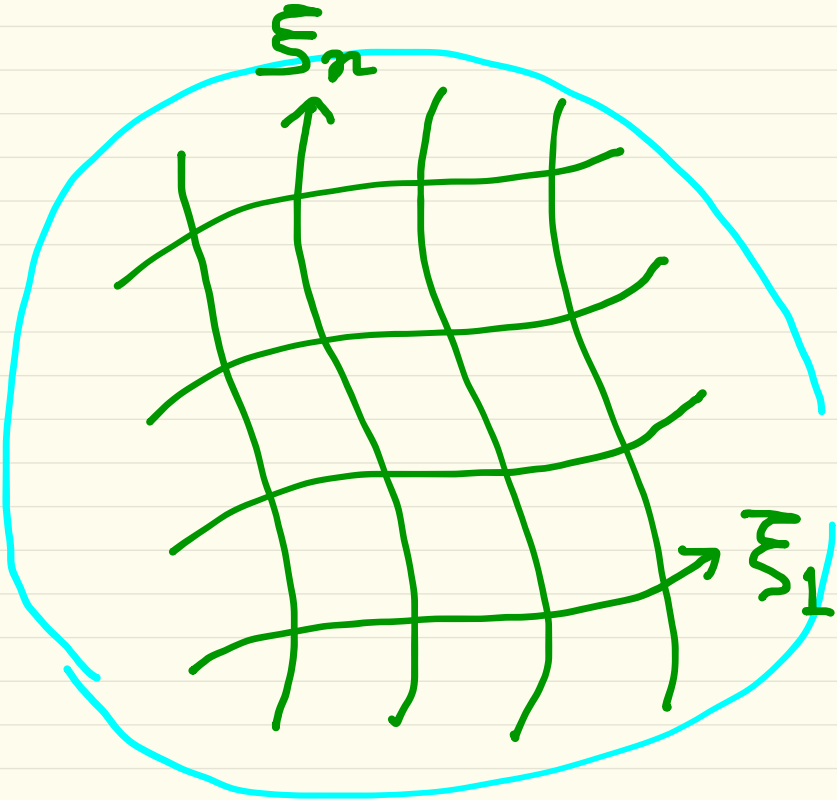


$$D[P:Q] \geq 0$$

distance

$$D[P:Q] \neq D[Q:P]$$

Manifold



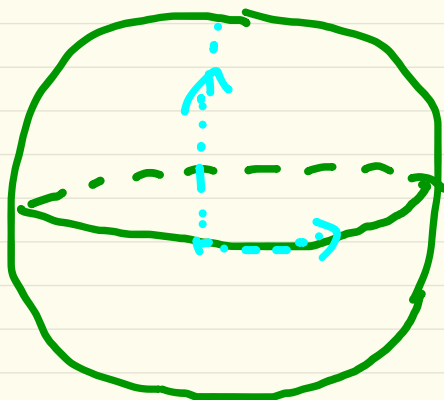
coordinate system

$$\mathcal{A} = (\xi_1, \dots, \xi_n)$$

Euclidean space



Sphere

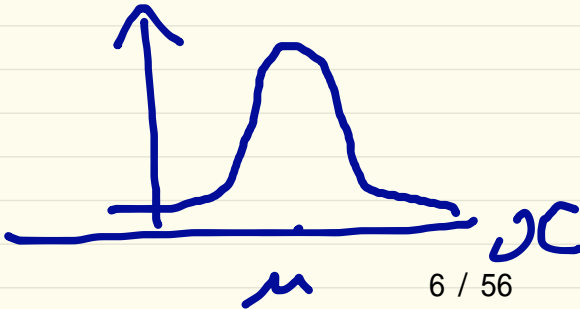
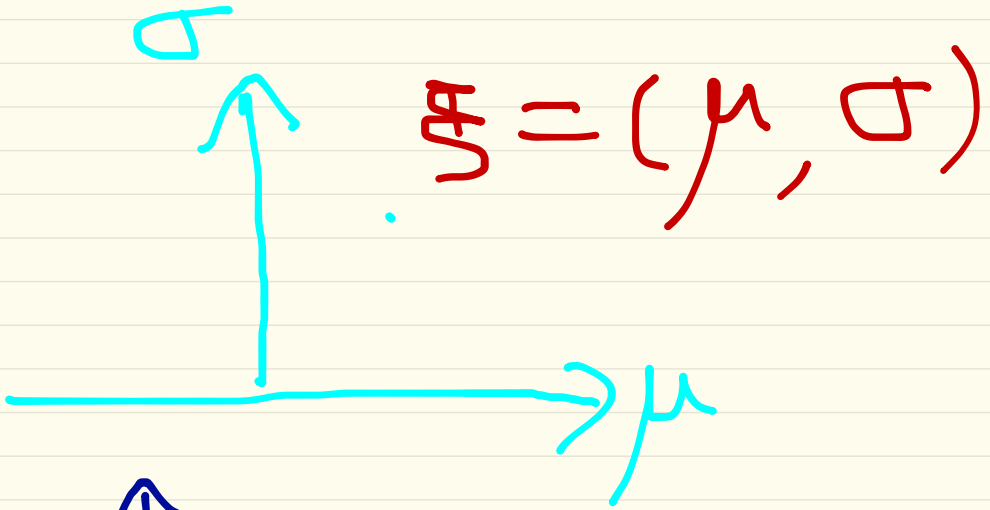


latitude
longitude

Probability Distributions

Gaussian distribution

$$P(x, \xi) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{(x-\mu)^2}{2\sigma^2}\right\}$$

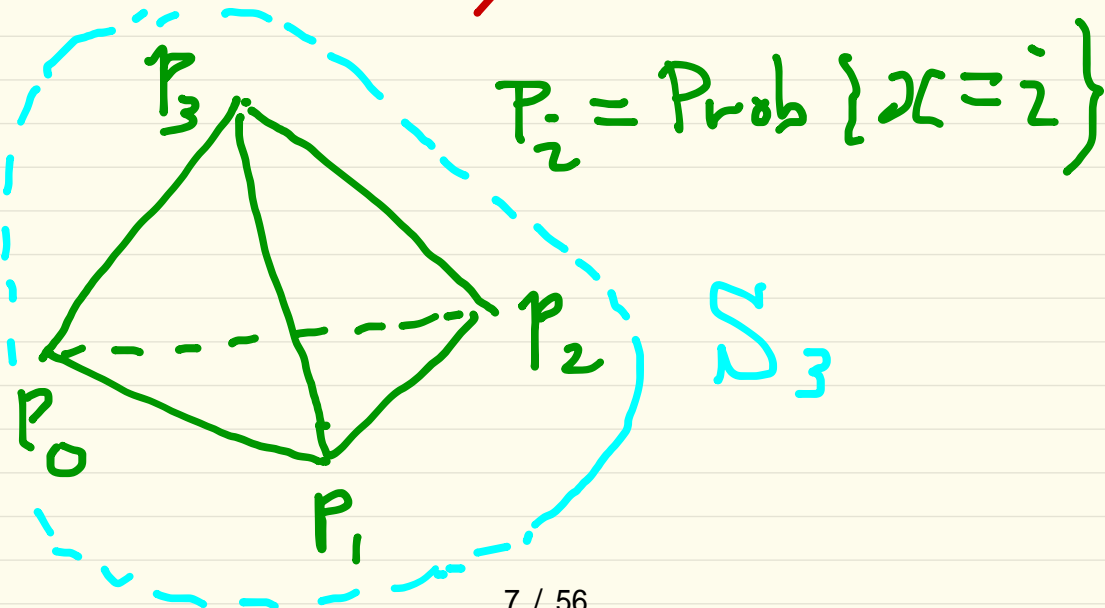


Probability Simplex S_n

$$S_n = \{p(x)\}$$

$$\mathcal{X} = \{0, 1, 2, \dots, n\}$$

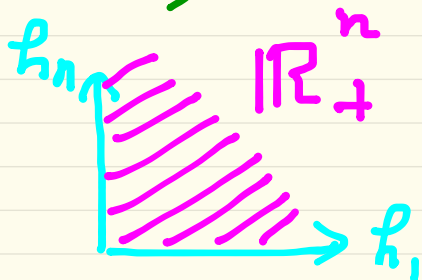
$$P = (p_0, \dots, p_n)$$



histgram

$$h = (h_1, \dots, h_n), \quad h_i > 0$$

$$\mathbb{R}_+^n$$



vision

$$S(x, y)$$

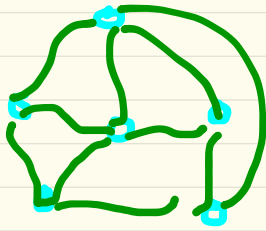
$$S_{ij} = S(i, j)$$

$$\mathbb{R}_+^{n^2}$$

Positiv-definite matrix

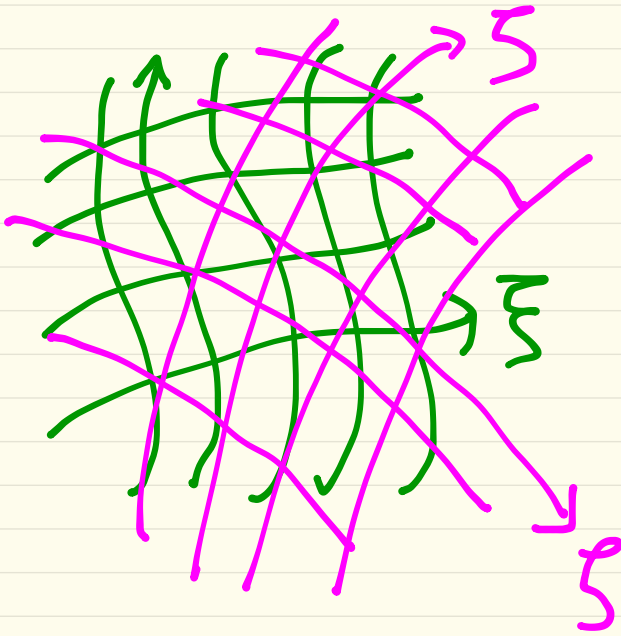
$\{P\}$ $P_{ij}, (i \leq j)$

Neural networks



$\{w_{ij}\}$

Coordinate transformation



$$\xi = f(\eta)$$

{ invariant
convenient

$$\xi_i = f_i(\xi_1, \dots, \xi_n)$$

Manifold with Divergence

$$\mathcal{D}[P:Q] \quad \mathcal{D}[\xi_P:\xi_Q]$$

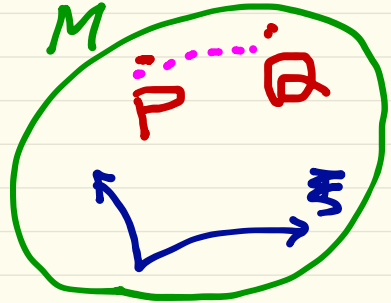
$$1) \mathcal{D}[P:Q] \geq 0 \quad ; \quad 0 \text{ iff } P=Q$$

$$2) \mathcal{D}[P:P+dP] = \frac{1}{2} g_{ij} d\xi^i d\xi^j$$

Positive-definite

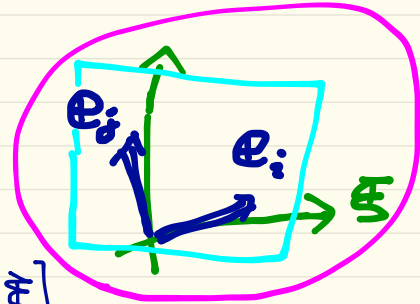
$$\mathcal{D}[P:Q] \neq \mathcal{D}[Q:P]$$

in general



Riemannian metric

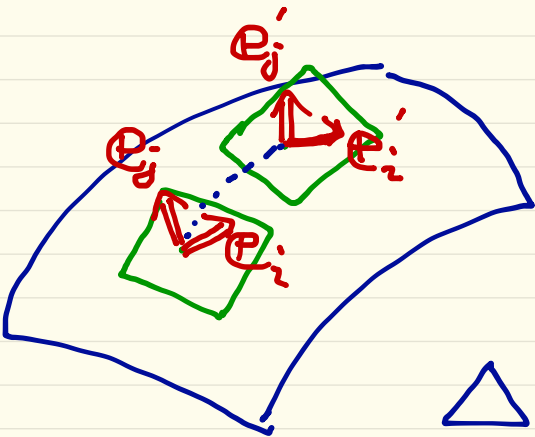
$$e_i = \frac{\partial}{\partial x_i} \quad \langle e_i, e_j \rangle = g_{ij}$$



$$ds^2 = g_{ij} dx_i dx_j = \frac{1}{2} D[x : x + dx]$$

T_{ijk} : cubic, symmetric

アフィン接続

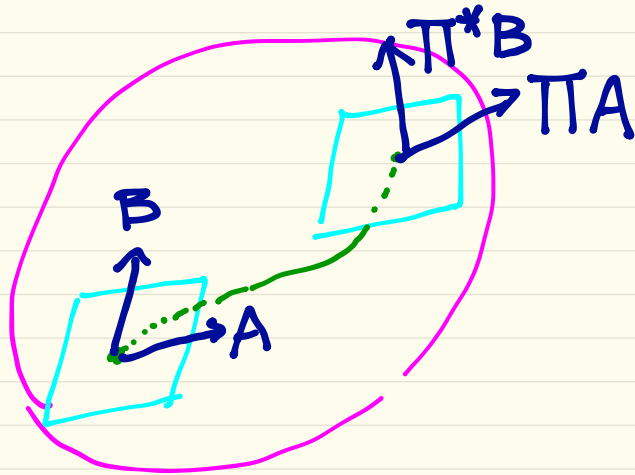


$$e_i' \sim e_i$$

$$\Delta e_i = \pi e_i' - e_i$$

$$\nabla_{e_j} e_i = \Gamma_{ji}^k e_k$$

Dual connections (Γ, Γ^*) (∇, ∇^*)



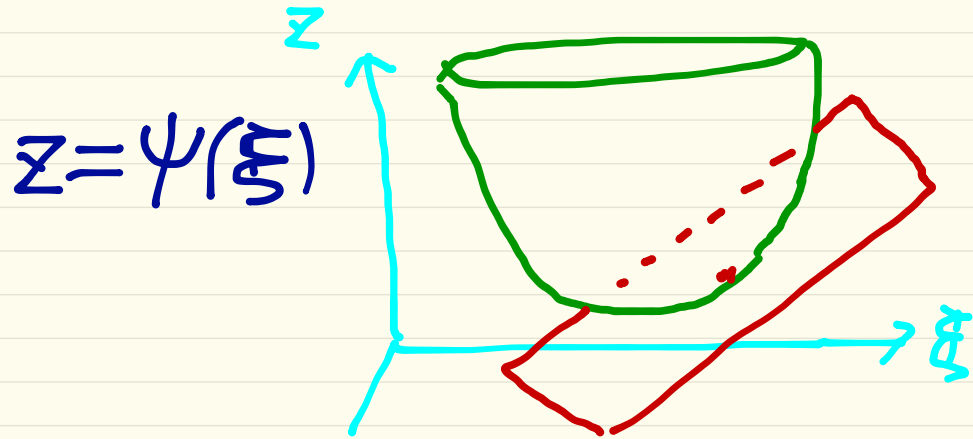
Parallel transport

$\pi A, \pi^* B$

$$\langle A, B \rangle = \langle \pi A, \pi^* B \rangle$$

$(\langle A, B \rangle = \langle \pi A, \pi B \rangle) : \text{Levi-Civita.}$

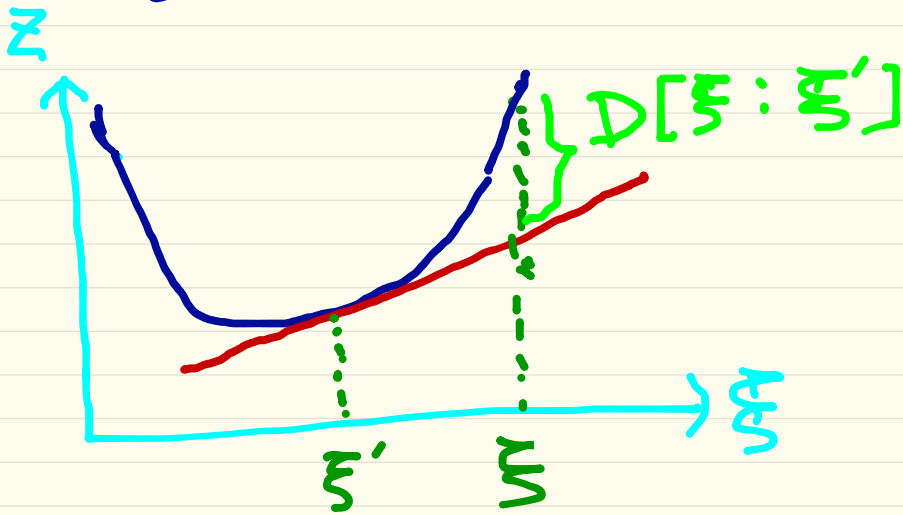
Convex Function



$$\psi(\alpha x_1 + (1-\alpha)x_2) \leq \alpha \psi(x_1) + (1-\alpha)\psi(x_2)$$

$$g_{ij} = \frac{\partial^2 \psi(x)}{\partial x_i \partial x_j} > 0$$

Bregman Divergence



$$z = \psi(x') + \nabla \psi(x') \cdot (x - x')$$

$$D[x: x'] = \psi(x) - \psi(x') - \nabla \psi(x') \cdot (x - x')$$

$$D_{ij} = \frac{\partial^2 \psi(x)}{\partial x_i \partial x_j} > 0$$

Examples

$$\psi(\xi) = \frac{1}{2} \sum \xi_i^2 \Rightarrow \text{Euclid}$$

$$\psi(\xi) = - \sum \log \xi_i$$

$$\psi(p(x)) = \int p(x) \log p(x) dx$$

$$D[p(x) : q(x)] \quad \text{KL-divergence}$$

$$= \int p(x) \log \frac{p(x)}{q(x)} dx$$

指數型分布族

曲指數型分布族

$$p(x, \theta) = \exp\{\theta \cdot x - \psi(\theta)\}$$

$\psi(\theta)$: 凸函數

$$g_{ij} = \frac{\partial^2}{\partial \theta^i \partial \theta^j} \psi(\theta)$$

$$T_{ijk} = \frac{\partial^3}{\partial \theta^i \partial \theta^j \partial \theta^k} \psi(\theta)$$

廣義空間

flat-divergence

⇒ exponential family

Banerjee et al.

$$p(x, \theta) = \exp \{ \theta \cdot x - \psi(\theta) \}$$

$$\eta = \nabla \psi(\theta) = E[x]$$

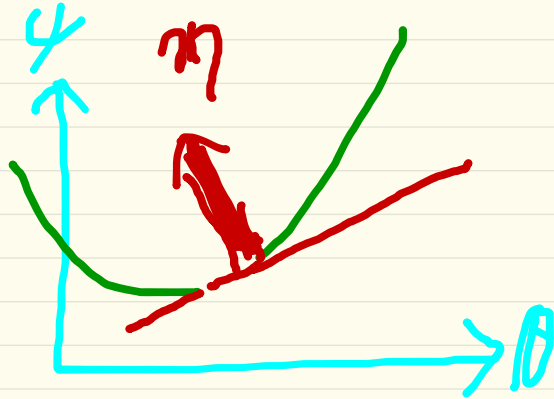
$$\mathcal{D}[\eta : \eta'] = \psi(\theta) + \varphi(\eta') - \theta \cdot \eta \quad \theta(\eta)$$

$$p(x, \theta) = \exp \{ -\mathcal{D}[x : \eta] \} b(x)$$

Legendre Transformation

$$\eta = \nabla \psi(\theta)$$

$$\theta = \nabla \varphi(\eta)$$



$$\underline{\theta \Leftrightarrow \eta}$$

$$\psi(\theta) + \varphi(\eta) - \theta \cdot \eta = 0$$

$$\mathcal{D}[\theta : \theta'] = \psi(\theta) + \varphi(\eta') - \theta \cdot \eta'$$

$$\varphi(\eta) = \max_{\theta} \{ \theta \cdot \eta - \psi(\theta) \}$$

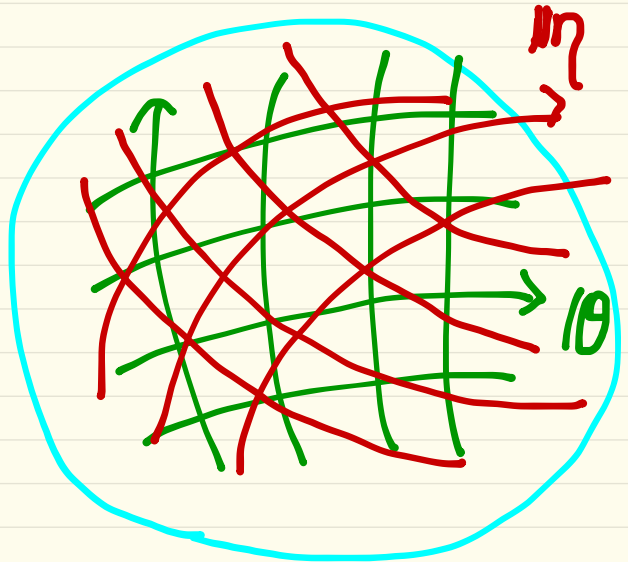
Affine Coordinates

flatt (θ, η)

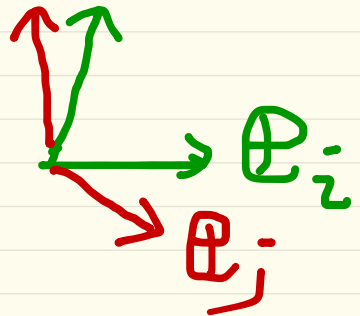
θ : flat

η : dual flat

biorrhogonal



$$\langle e_i, e^{*j} \rangle = \delta_{ij}$$



Riemmanian metric

$$d\theta = \sum d\theta_i E_i$$

$$d\eta = \sum d\eta_i E_i^*$$

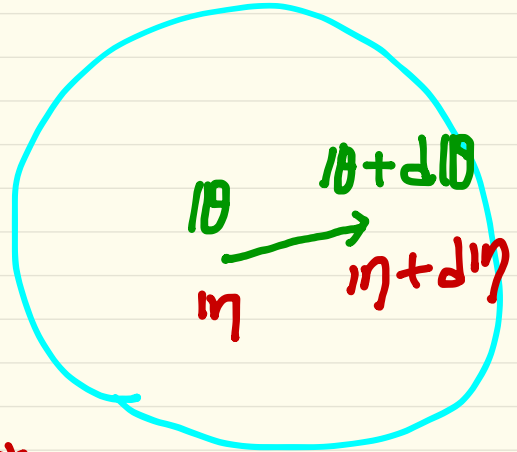
$$ds^2 = \langle d\theta, d\theta \rangle$$
$$= \sum g_{ij} d\theta_i d\theta_j$$

$$g_{ij} = \langle E_i, E_j \rangle$$

$$ds^2 = \sum g_{ij}^* d\eta_i d\eta_j$$

$$g_{ij}^* = \langle E_i^*, E_j^* \rangle$$

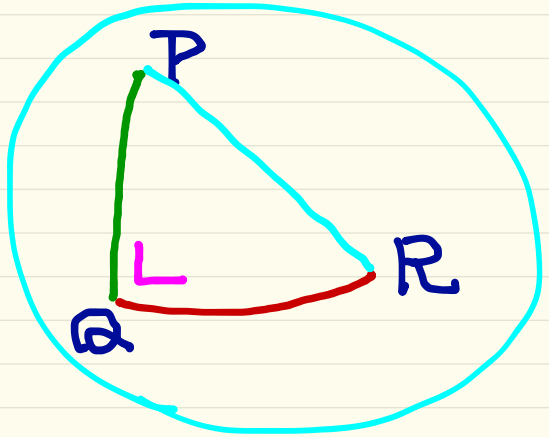
$$G = G^{*-1}$$



Pythagorean Theorem

— geodesic

— dual geodesic



$$D[P:Q] + D[Q:R] = D[P:R]$$

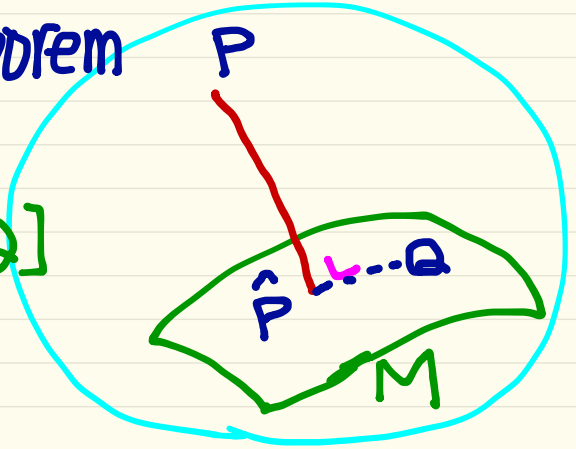
Euclidean space

$$\Psi(\theta) = \frac{1}{2} \sum \theta_i^2 : \eta_i = \theta_i$$

Proof

Projection Theorem

$$\hat{P} = \operatorname{argmin}_{Q \in M} D[P:Q]$$



$$D^*[P:Q] = D[Q:P]$$

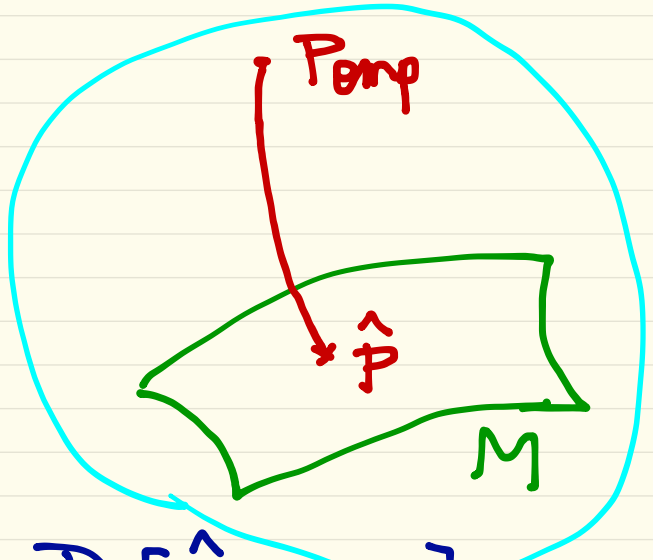
\uparrow
 $\varphi(\eta)$

$$\hat{P}^* = \operatorname{argmin}_{Q \in M} D[Q:P]$$

Applications: Statistical Inference

$$M = \{P(\alpha, \xi)\}$$

$$x_1, \dots, x_N$$



$$\hat{\xi} = \operatorname{argmin}_{\Theta} D[\hat{P}_{emp} : \Theta]$$

$\Theta = P(\alpha, \xi)$

D : KL-divergence : MLE (maximum likelihood estimator)

Invariance :

Probability distributions

$D[P(x) : f(x)]$ Information monotone

$$y = R(x)$$

$$p(x) \rightarrow \bar{p}(y) dy = p(x) dx$$

$$D[P(x) : f(x)] \geq \bar{D}[\bar{P}(y) : \bar{f}(y)]$$

y : sufficient statistics

$$\Leftrightarrow D = \bar{D}$$

$$p(x, \xi) = \bar{p}(y, \xi) \Gamma(x)$$

f-divergence

$$f(1) = f'(1) = 0, \quad f''(1) = 1$$

$f(u)$: convex function

$$D_f [P(x) : Q(x)] = \int P(x) f\left(\frac{Q(x)}{P(x)}\right) dx$$

invariant divergence

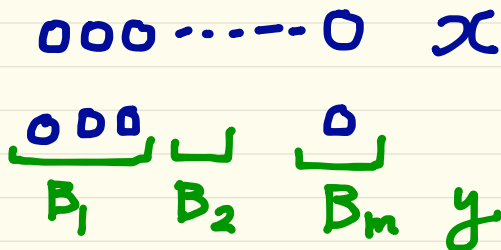
$$D_f [Q(x) : P(x)] = D_{f^*} [P(x) : Q(x)]$$

$$f^*(u) = u f\left(\frac{1}{u}\right)$$

$$f = -\log u \quad \text{KL-divergence}$$

S_n : discrete

$P = (p_0, p_1, \dots, p_n)$. $P_i = \text{Prob}\{x=i\}$



coarse graining

$$P \rightarrow \bar{P}$$
$$P(x) \rightarrow \bar{P}(y)$$

$$\bar{P}_\alpha = \text{Prob}\{y=\alpha\}$$
$$= \text{Prob}\{x \in B_\alpha\}$$
$$= \sum_{i \in B_\alpha} p_i$$

Information monotone

$$D[P:Q] \geq \bar{D}[\bar{P}:\bar{Q}]$$

$y = k(x)$ sufficient

$$\text{Prob}_P\{x | y \in B_\alpha\} = \text{Prob}_Q\{x | y \in B_\alpha\}$$

$$D[P:Q] = \bar{D}[\bar{P}:\bar{Q}]$$

decomposable divergence

$$D[P:Q] = \sum k(p_i, q_i)$$

Theorem decomp. invariant d

$$: D_f[P:Q] = \sum p_i f\left(\frac{q_i}{p_i}\right)$$

•

Flat & Invariant Divergence

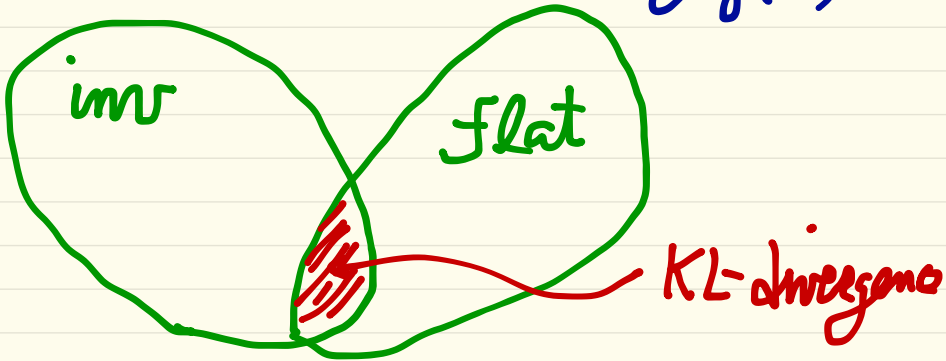
↑
Bregman

↑
f-

$$\begin{cases} \theta = \log \frac{p_i}{p_0} \\ \eta = p_i \end{cases}$$

KL-divergence

$$D_{KL}[P: Q] = \int P(x) \log \frac{P(x)}{Q(x)}$$



α -divergence : invariant

$$f_{\alpha}(u) = \frac{-4}{1-\alpha^2} u^{\frac{1+\alpha}{2}}$$

$$D_{\alpha}[P:Q] = \sum_i \left\{ \frac{1-\alpha}{2} p_i + \frac{1+\alpha}{2} q_i - p_i^{\frac{1-\alpha}{2}} q_i^{\frac{1+\alpha}{2}} \right\}$$

$$= 1 - \sum p_i^{\frac{1-\alpha}{2}} q_i^{\frac{1+\alpha}{2}} \quad : \text{p.d.}$$

$\alpha = -1$ KL-divergence

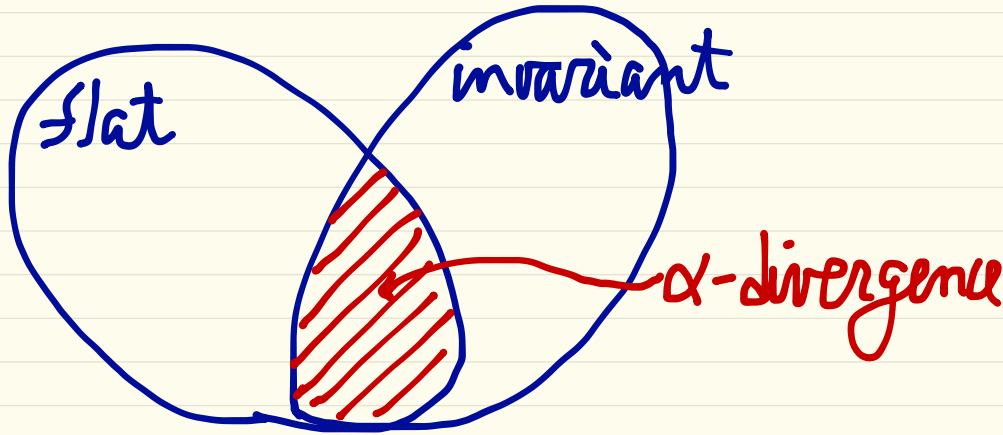
$\alpha = 1$ dual KL

$\alpha = 0$ Hellinger

$$\frac{1}{2} \sum_i (\sqrt{p_i} - \sqrt{q_i})^2$$

Flat & Invariant Div.

in \mathbb{R}_+^n : positive measure



$$\theta_i = p_i^{\frac{1+\alpha}{2}}, \quad \eta_i = p_i^{\frac{1-\alpha}{2}}$$

$$\mathcal{D}_\alpha [P : Q] = \mathcal{D}_{-\alpha} [Q : P]$$

$$\psi(\theta) = \sum \theta_i^{\frac{2}{1+\alpha}}, \quad \varphi(\eta) = \sum \eta_i^{\frac{2}{1-\alpha}}$$

$\alpha \leftrightarrow -\alpha$ duality

α -structure

α -mean

α -family of prob. distributions

α -projection

α -optimality

Tsallis q -entropy

$$H(\mathbb{P}) = \frac{1}{1-q} \left(\sum p_i^q - 1 \right)$$

$$\alpha = 2q - 1$$

$$\left| \frac{1+\alpha}{p_i^2} \right|$$

α -mean

$$x, y > 0$$

$$m_f(x, y) = f^{-1}\left(\frac{f(x) + f(y)}{2}\right)$$

scale-free

$$m_f(cx, cy) = c m_f(x, y)$$

$$f_\alpha(u) = \begin{cases} u^{\frac{1-\alpha}{2}} \\ \log u, & \alpha = 1 \end{cases}$$

$\alpha = 1$: geometric mean \sqrt{xy}

$\alpha = -1$: arithmetic mean $\frac{x+y}{2}$

$\alpha = 0$: $\frac{1}{2} \left(\frac{1}{2}(x+y) + \sqrt{xy} \right)$

$\alpha = 3$: harmonic mean $\frac{2}{\frac{1}{x} + \frac{1}{y}}$

$\alpha = \infty$: $\min\{x, y\}$
fuzzy

$\alpha = -\infty$: $\max\{x, y\}$

$$m_{\alpha}(x, y) \geq m_{\alpha'}(x, y), \quad \alpha \leq \alpha'$$

pessimistic mean : optimistic mean

α -family of Prob. distr.

$$f_1(x), \dots, f_m(x)$$

\Rightarrow

$$P_\alpha(x; w) = C f_\alpha^{-1} \left\{ \sum_{i=1}^m w_i f_\alpha(f_i(x)) \right\}$$

$$\alpha = -1 \quad P_\alpha(x) = \sum w_i f_i(x)$$

mixture family

$$\alpha = 1 \quad P_\alpha(x) = \exp \{ \sum w_i \log f_i(x) - \psi \}$$

exp. family

α -integration of $g_1(x), \dots, g_m(x)$

$$P(x) = f_\alpha^{-1} \left\{ \sum w_i f_\alpha \{ p_i(x) \} \right\}$$

$$R [P(x)] = \sum w_i D [g_i(x) : P(x)]$$

$$\min R_\alpha [P(x)]$$

: α -integration

mixture of
experts

$$\begin{array}{c} g_2 \cdots g_1 \\ g_2 \cdots P(x) \cdots g_1 \end{array}$$

flat divergence (non-invariant)

(α, β) -divergence : \mathbb{R}_+^n

$$D_{\text{eq}}[P:Q] = \frac{1}{\alpha\beta(\alpha+\beta)} \sum \left\{ \alpha P_i^{\alpha+\beta} + \beta Q_i^{\alpha+\beta} - (\alpha+\beta) P_i^\alpha Q_i^\beta \right\}$$

$$\theta_i = \frac{1}{\alpha} P_i^\alpha, \quad \eta_i = \frac{1}{\beta} P_i^\beta$$

$$\psi(\theta) = c \sum \theta_i^{\frac{\alpha+\beta}{\alpha}}, \quad \varphi(\eta) = c \sum \eta_i^{\frac{\alpha+\beta}{\beta}}$$

(u, v) -divergence

$u(s), v(s)$: monotone incr.

$$\theta_i = u(p_i), \quad \eta_i = v(p_i)$$

$$\psi(\theta) = \sum \int_{p_i}^{p_{i+1}} v(p) u'(p) dp$$

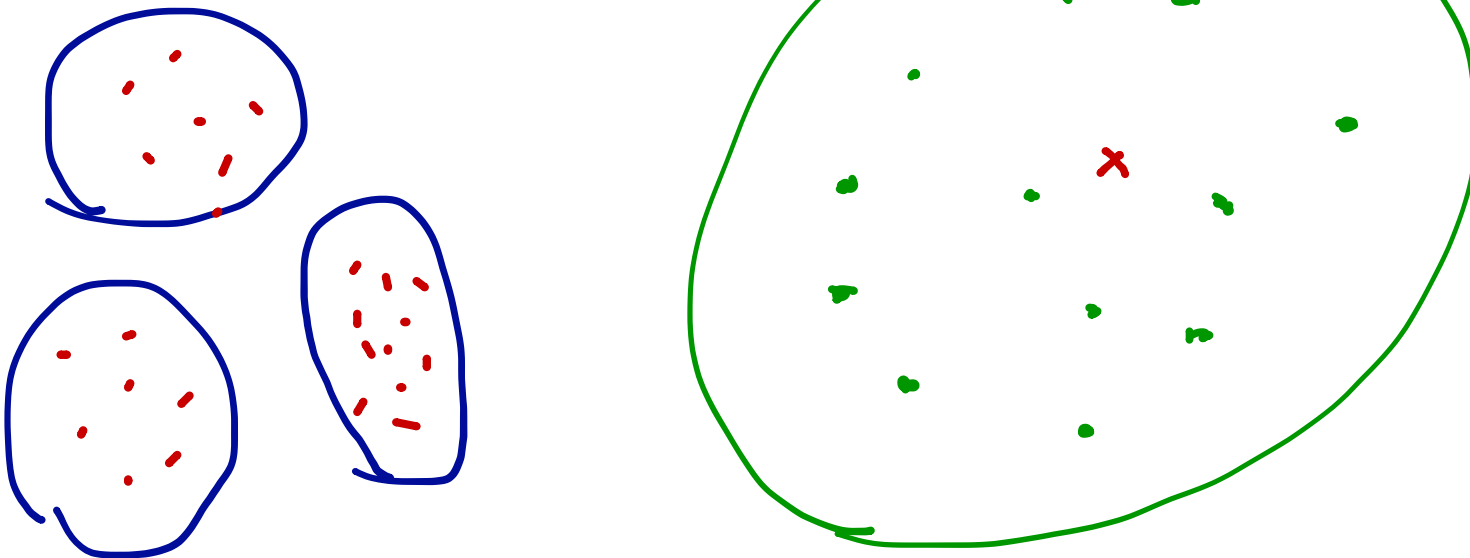
$$\varphi(\eta) = \sum \int_{p_i}^{p_{i+1}} u(p) v'(p) dp$$

$$\mathcal{D}[p; \theta] = \sum_i \left[\int_{p_i}^{p_{i+1}} v'(p) u(p) dp + \int_{p_i}^{p_{i+1}} u v' dp - u(p_i) v(p_{i+1}) \right]$$

Center of a cluster

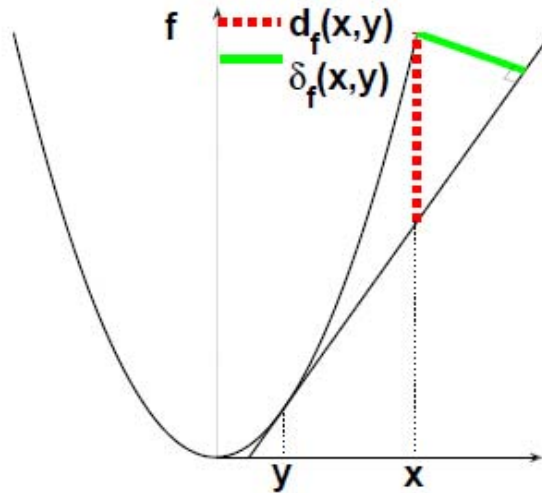
$$\mathbf{x}^* = \arg \min \sum_i D[\mathbf{x}, \mathbf{x}_i]$$

K-means clustering



Total Bregman Divergence

$$TD[x : y] = \frac{D[x : y]}{\sqrt{1 + \|\nabla \psi\|^2}}$$



- rotational invariance
- conformal geometry

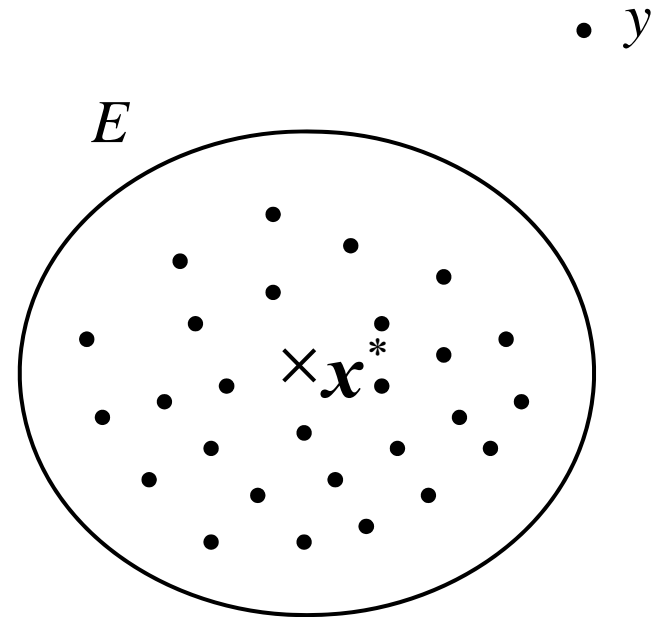
Figure: $d_f(x, y)$ (dotted red line) is BD, $\delta_f(x, y)$ (bold green line) is TBD, and the two arrows indicate the coordinate system. Note that $d_f(x, y)$ changes with rotation unlike $\delta_f(x, y)$ which is invariant to rotation.

Clustering : t -center

$$E = \{x_1, \dots, x_m\}$$

T-center of E

$$\mathbf{x}^* = \arg \min \sum_i TD[\mathbf{x}, \mathbf{x}_i]$$



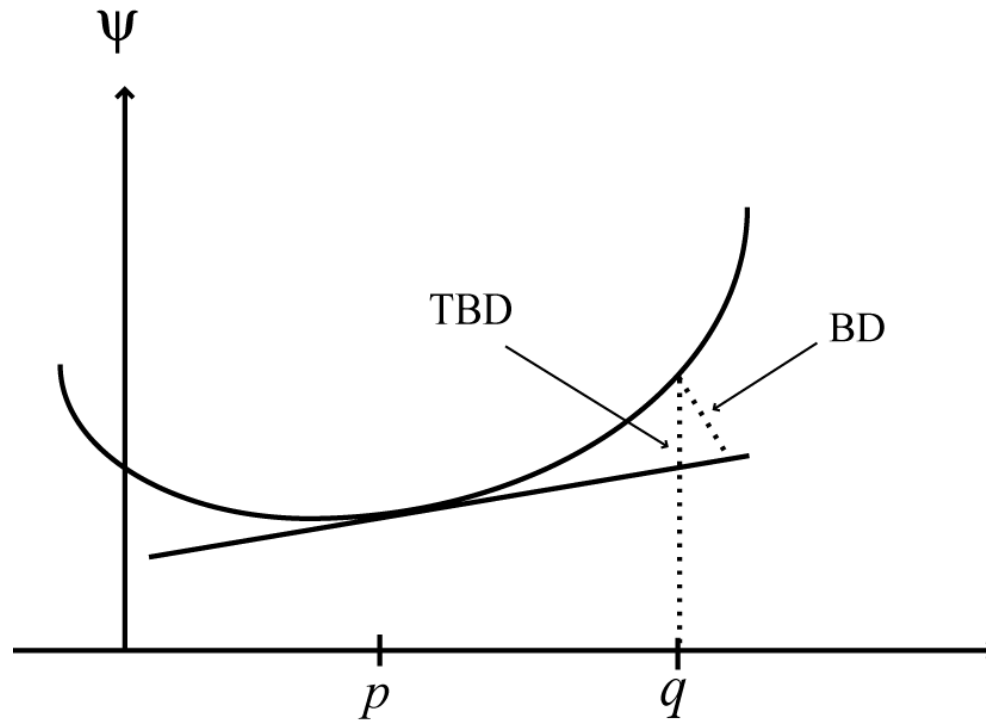
t -center \mathbf{x}^*

$$\nabla \psi(\mathbf{x}^*) = \frac{\sum w_i \nabla \psi(\mathbf{x}_i)}{\sum w_i}$$

$$w_i = \frac{1}{\sqrt{1 + \|\nabla \psi(\mathbf{x}_i)\|^2}}$$

Total Bregman divergence (Vemuri)

$$\text{TBD}(p : q) = \frac{\varphi(p) - \varphi(q) - \nabla \varphi(q) \cdot (p - q)}{\sqrt{1 + |\nabla \varphi(q)|^2}}$$



Conformal change of divergence

$$\tilde{D}(p : q) = \sigma(p) D[p : q]$$

$$\tilde{g}_{ij} = \sigma(p) g_{ij}$$

$$\tilde{T}_{ijk} = \sigma(T_{ijk} + s_k g_{ij} + s_j g_{ik} + s_i g_{jk})$$

$$s_i = \hat{\partial}_i \log \sigma$$

t-center is robust

$$E^* = \{\mathbf{x}_1, \dots, \mathbf{x}_n; \mathbf{y}\}$$

$$\tilde{\mathbf{x}}^* = \mathbf{x}^* + \varepsilon \mathbf{z}(\mathbf{x}^*; \mathbf{y}), \quad \varepsilon = \frac{1}{n}$$

influence function $\mathbf{z}(\mathbf{x}^*; \mathbf{y})$

$|\mathbf{z}| < c$ as $|\mathbf{y}| \rightarrow \infty$: robust

Positive-Definite Matrices

(α, β) -divergence in $\mathcal{P} = \{P > 0\}$

$$D_{\alpha, \beta} [P : Q] = \text{tr} \left\{ \frac{\alpha}{\alpha + \beta} P^{\alpha + \beta} + \frac{\beta}{\alpha + \beta} Q^{\alpha + \beta} - P^{\alpha} Q^{\beta} \right\}$$

$D_{u, v}$

flat divergence in S_n

: escort probability &
conformal geometry

$$h_\alpha(P) = \sum P_i^{\frac{1+\alpha}{2}} \quad (\alpha\text{-exp. fam.})$$

$$\tilde{D}_\alpha[P:Q] = \frac{2}{1-\alpha} \frac{1}{h_\alpha(Q)} \left[1 - \sum P_i^{\frac{1+\alpha}{2}} Q_i^{\frac{1-\alpha}{2}} \right]$$

$$Q_i = \frac{2}{1-\alpha} \left[p_i^{\frac{1-\alpha}{2}} - p_0^{\frac{1-\alpha}{2}} \right]$$

$$\eta_i = \frac{1}{h_\alpha(P)} P_i^{\frac{1+\alpha}{2}} \approx \tilde{P}$$

$$\tilde{g}_{ij}(\theta) = \frac{1}{h_\alpha(\theta)} g_{ij}(\theta)$$

conformal : unique (α -escort)

Divergence and Geometry

$$\mathcal{D}[\xi : \xi'] \quad \nabla_{\xi} = \frac{\partial}{\partial \xi_i} \cdot \nabla_{\xi'} = \frac{\partial}{\partial \xi'_i}$$

Riemannian Metric

$$g_{ij} = -\nabla_{\xi_i} \nabla_{\xi_j} \mathcal{D}[\xi : \xi']_{\xi = \xi'} \quad : \text{positive-definite}$$

cubic tensor

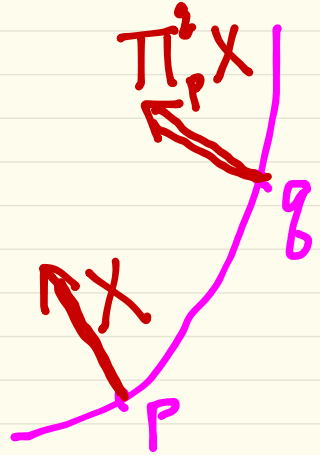
$$T_{ijk} = \nabla_{\xi_i} \nabla_{\xi_j} \nabla_{\xi_k} \mathcal{D} - \nabla_{\xi_i} \nabla_{\xi_j} \nabla_{\xi_k} \mathcal{D}$$

$$\mathcal{D} \rightarrow \{M, g, T\} : T \text{ symmetric}$$

$\{M, g\}$

covariant derivatives

$$\nabla \iff \nabla^*$$



$$\Pi_P^g X, \Pi_P^{*g} X \quad : \text{parallel}$$

U U U U U U U

Dual Affine Connections

$$\Gamma_{ijk} = \{i, j, k\} - \frac{1}{2} T_{ijk}$$

$$\Gamma_{ijk}^* = \{i, j, k\} + \frac{1}{2} T_{ijk}$$

$$\Gamma_{ijk}^\alpha = \{i, j, k\} - \frac{\alpha}{2} T_{ijk}$$

$\pm \alpha$ duality

$$\mathfrak{D}_Z \langle X, Y \rangle = \langle \nabla_Z X, Y \rangle + \langle X, \nabla_Z^* Y \rangle$$

$$\langle X, Y \rangle_p = \langle \pi_p^! X, \pi_p^{*!} Y \rangle_Z$$

Two geodesics

$$\nabla_{\dot{\xi}} \dot{\xi}(t) = 0 \quad \xi(t)$$

$$\nabla_{\dot{\xi}}^* \dot{\xi}(t) = 0$$

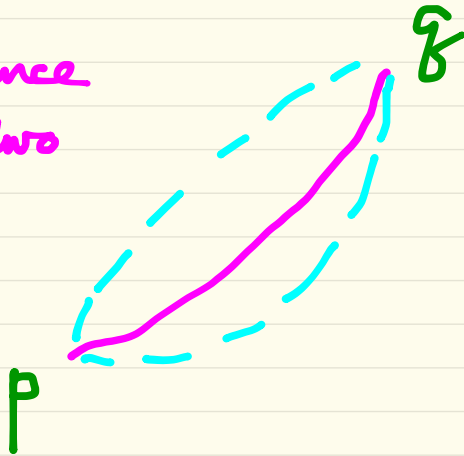
$$\ddot{\xi}_i + \sum \Gamma_{kjz} \dot{\xi}_k \dot{\xi}_j = 0$$

Euclidean : minimal distance
straight

Riemannian : Levi-Civita connection

dual geometry :

minimal distance
splits into two



Flat Manifold & Canonical Divergence

dually flat: $R=0 \Leftrightarrow R^*=0$

\Rightarrow affine coordinates: θ, η

\Rightarrow convex functions: $\psi(\theta), \varphi(\eta)$

canonical divergence

$$D[\theta : \theta'] = \psi(\theta) + \varphi(\eta') - \theta \cdot \eta'$$

manifold of prob. distributions

invariance & flat \Rightarrow KL-divergence

flat-divergence

⇒ exponential family

Banerjee et al.

$$p(x, \theta) = \exp \{ \theta \cdot x - \psi(\theta) \}$$

$$\eta = \nabla \psi(\theta) = E[x]$$

$$\mathcal{D}[\eta : \eta'] = \psi(\theta) + \varphi(\eta') - \theta \cdot \eta \quad \theta(\eta)$$

$$p(x, \theta) = \exp \{ -\mathcal{D}[x : \eta] \} b(x)$$

Le Theorem

$\{M, \mathcal{G}, \mathcal{T}\}$:

realization in probability model

$$M = \{P(x, \xi)\}$$

embedding
curvature

invariance \Rightarrow

uniqueness of

$\mathcal{G}_{ij}, \mathcal{T}_{ijk}$

Hessian manifold (Shima)

$$g_{ij}(\xi) = \nabla_{\xi_i} \nabla_{\xi_j} \psi(\xi)$$

$$\{M, g\} \Rightarrow \{M, g, T\}$$

dually flat ?

given $g_{ij} \Rightarrow \exists T_{ijk} : \text{flatten}$